

MODELING AND CONTROL OF NON-LINEAR SYSTEMS USING INTELLIGENT TOOLS

by

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Submitted

in fulfillment of the requirements of the degree of Doctor of Philosophy

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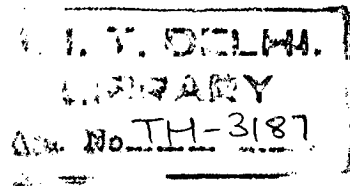


Indian Institute of Technology, Delhi

January 2005

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- nonlinear control
- fuzzy logic

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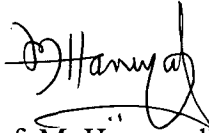


Certificate

This is to certify that the thesis entitled “*Modeling and Control of Non-Linear Systems using Intelligent Tools*” being submitted by **Smriti Srivastava** for the award of the degree of the **Doctor of Philosophy** to Indian Institute of Technology, Delhi is a record of the bonafide research work she has carried out under our supervision. The results contained in this have not been submitted to any other University or Institute for the award of a degree or diploma.



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Acknowledgement

It is my great pleasure to express my appreciation to everyone who is directly or indirectly related with this thesis work. Many different people have made this thesis possible, none more so than my supervisors, Prof. M. Hanmandlu and Prof. A.N. Jha who gave me firm understanding of use of intelligent tools and always helped me out from the mathematical hurdles. I am deeply grateful for all their support and encouragement during the entire course of this work.

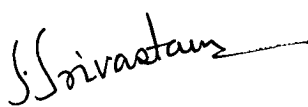
I would also like to express my thanks to SRC members Prof. R. Balasubramaniam and Dr. R.K.P. Bhatt and Dr. I.N. Kar for their timely and useful suggestions.

I owe many thanks to Dr. Ranjeet Singh, Director, NSIT, for sponsoring my Ph.D. program at IIT-Delhi and for providing a congenial environment at my workplace.

I cannot forget to mention the name of Madhusudan Singh, who is my student, colleague and research mate. He participated in many technically stimulating and invigorating discussions during the course of this thesis. Also I would like to express my gratitude to Mr. Hari Sahaya Singh of Control Engineering Laboratory at NSIT.

I want to express my sincere thanks to my husband Sanjay who constantly supported me throughout this uphill task. My sincere thanks are to my father-in-law and mother-in-law for their constant understanding. I also want to express special thanks to my daughter Shefali who gave me an immense feeling of freshness at all times. She was extremely patient and permitted me to spend time on this work when in reality she needed my attention.

Finally before closing this I cannot but think of anyone else other than my parents who have provided me with the foundation, virtues and values for which I stand today.


Smriti Srivastava

Abstract

The thesis presents several studies aimed at enhancing the capabilities of fuzzy models by taking in to account the specific characteristics of the given input-output data and by bringing to the fore the hidden dynamically varying relationship. The characteristics of the input-output signals though explored in the signal processing area by the wavelets are not utilized in the fuzzy domain. In this thesis, we have made use of two properties of wavelets, viz., compression and multiresolution in the framework of Takagi-Sugeno model to design two architectures of Fuzzy Wavelet Neural Networks (FWNN). These architectures are then used for identification and control. The control is achieved through Fuzzy PI and neural network controller.

In the next study, we have bent upon devising an efficient controller that consists of linear and nonlinear parts. Several candidates have been used for these two parts and finally the combination of FTF serving as linear part and α -LMS and gradient descent learning serving as the nonlinear part in the neural learning came out with flying colors.

Our attention is then turned on to the treatment of non-additive fuzzy systems. The Takagi-Sugeno model combines the information from independent input sources. In many realistic applications, the assumption of independence doesn't hold good. In this thesis, we have addressed this problem at length and proposed Choquet fuzzy integral based identification and control. The modification here is the replacement of consequent parts of fuzzy rules of TS model by Choquet integral. In this integral, the information from any two sets is combined non-additively with the inclusion of λ -parameter. As there are problems with its solution we have used a q -measure which is a generalization of λ -measure and it involves splitting a fuzzy set into two. Next, to improve the convergence of the λ -parameter, we have proposed four-measure by which we split up a fuzzy set into four. This four measure is then

extended to n -measure and complexity of different fuzzy measures vs. performance is also studied.

We have also made an extensive use of Choquet integral in the reformulation of learning law and the fuzzy curve approach intended for structure determination of non-additive fuzzy systems.

Finally, the dynamics of the input-output behavior is realized through the fuzzy model by modifying the consequent part of the fuzzy rule of TS model. In this formulation, the inputs and outputs are expressed in terms of state space type equations. The approaches presented in the thesis have been validated by applying them on benchmark problems.

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